

Recall: Second order linear homogeneous ODE w/ const coeff.  
 $ay'' + by' + cy = 0$ ,  $a, b, c$  real numbers

Characteristic equation:  $ar^2 + br + c = 0$

Characteristic roots:  $r_1, r_2$

Case I:  $r_1, r_2$  real distinct.

General solution  $y = C_1 e^{r_1 t} + C_2 e^{r_2 t}$

Case II:  $r_1 = r_2 = r$  repeated (automatically real)

General solution  $y = C_1 e^{rt} + C_2 t e^{rt}$

Case III:  $r_1 \neq r_2$  complex. Write  $r_1 = \alpha + i\beta, r_2 = \alpha - i\beta$

General solution  $y = C_1 e^{\alpha t} \cos \beta t + C_2 e^{\alpha t} \sin \beta t$

Left overs for the previous class: repeated root case. how comes the  $t$  factor in the other solution.

### Variation of Parameters

Philosophy: If you know one solution  $y_1$ , then since the ODE is linear,  $\uparrow cy_1$  will also be a solution for any number  $c$ . parameter.

Change this numeric parameter into a function, i.e., set  $y_2(t) = u(t) \cdot y_1(t)$ , then plug it into the ODE to find  $u(t)$ .

① Application to homogeneous ODE.

Knowing  $y_1$  is a solution to

$$y'' + p(t)y' + q(t)y = 0$$

Set  $y_2(t) = u(t)y_1(t)$ , put it back to the ODE.

$\Rightarrow$  another ODE with order reduced by one that leads to  $u(t)$ .

$$y_2'' + py_2' + qy_2 = (uy_1)'' + p(uy_1)' + q(uy_1)$$

$$(uy_1)' = u'y_1 + uy_1', \quad (uy_1)'' = u''y_1 + 2u'y_1' + uy_1''$$

$$= u''y_1 + 2u'y_1' + uy_1'' + p(u'y_1 + uy_1') + quy_1$$

$$= u''y_1 + u'(2y_1' + py_1) + u(y_1'' + py_1' + qy_1)$$

$y_1$  is a soln  $\Rightarrow y_1'' + py_1' + qy_1 = 0$

$$= u''y_1 + u'(2y_1' + py_1) = 0 \quad (\text{we set } y_2 \text{ as a soln})$$

In other words, if  $y_2 = uy_1$  is a solution, then  $u$  must satisfy

$$y_1u'' + (2y_1' + py_1)u' = 0$$

This can be regarded as a first order ODE concerning  $u'$ .

More precisely, set  $v = u'$ , then

$$y_1v' + (2y_1' + py_1)v = 0$$

We can solve  $v$  from this ODE  $\Rightarrow u$  (by integration)

$$\Rightarrow y_2 \quad (\text{by multiplying } u \text{ to } y_1) \Rightarrow \text{Gen. soln: } y = C_1y_1 + C_2y_2.$$

Example:  $y'' - 2ry' + r^2y = 0$ .  $r$  real number.

Know from char. eqn. that  $y = e^{rt}$  is a sol'n.

Set  $y_1 = u(t)$ ,  $y_1(t) = u \cdot e^{rt}$ . We know from above that  $u$  satisfies

$$y_1 u'' + (2ry_1' + py_1) u' = 0$$

$$\Rightarrow e^{rt} u'' + (2re^{rt} - 2re^{rt}) u' = 0 \Rightarrow e^{rt} u'' = 0 \Rightarrow u'' = 0$$

$$\text{Integrate: } u' = C_1$$

$$u' = 1 \quad (\text{Set } C_1 = 1)$$

$$\text{Integrate again: } u = C_1 t + C_2$$

$$u = t \quad (\text{Set } C_2 = 0)$$

$$y_1 = u y_1 = (C_1 t + C_2) e^{rt} = C_1 t e^{rt} + C_2 e^{rt} \quad y_2 = t e^{rt}.$$

This means  $C_1 t e^{rt} + C_2 e^{rt}$  will be another sol'n for any  $C_1, C_2$ .

When  $C_1 = 0, C_2 = 1$ , we recover  $y_1$ .

$$W(y_1, y_2) \neq 0$$

$\Rightarrow$  Gen. sol'n  $y = C_1 t e^{rt} + C_2 e^{rt}$ .

$$\begin{aligned} \text{Gen. sol'n } y &= C_1 y_1 + C_2 y_2 \\ &= C_1 e^{rt} + C_2 t e^{rt}. \end{aligned}$$

Rmk's: ① Normally when solving for  $u(t)$ , we normally will set those arbitrary constants as concrete numbers so as to simplify the computation. However if you don't do that, then  $y_2 = u y_1$  will give the general sol'n.

② When formulating the ODE concerning  $u$ , make sure your  $p$  comes from the **standard form**. Also notice that  $q$  is not used.

Example:  $ty'' - y' - 4t^3y = 0$ . Knowing  $y_1 = \sin(t^2)$  is a sol'n,  
Find the general solution.

Std. form:  $y'' - \frac{1}{t}y' - 4t^3y = 0$ .

Set  $y_2 = uy_1$ .  $y_1 = \sin(t^2)$ .  $y_1' = 2t\cos(t^2)$   $P = -\frac{1}{t}$

$$\sin(t^2) \cdot u'' + \left(4t\cos(t^2) - \frac{1}{t}\sin(t^2)\right)u' = 0.$$

$$\frac{u''}{u'} = \frac{4t\cos(t^2) - \frac{1}{t}\sin(t^2)}{-\sin(t^2)}$$

$$= -\frac{4t\cos(t^2)}{\sin(t^2)} + \frac{1}{t}$$

Integrate:  $\ln|u'| = \ln|t| - \int \frac{4t\cos(t^2)}{\sin(t^2)} dt$

$$\int \frac{4t\cos(t^2)dt}{\sin(t^2)} \xrightarrow[u=\sin(t^2)]{du=2t\cos(t^2)dt} \int \frac{2du}{u} = 2\ln|u| + C = 2\ln|\sin(t^2)| + C$$

$$= \ln|t| - 2\ln|\sin(t^2)| \quad \text{took } C = 0$$

$$\ln|u'| = \ln\left|\frac{t}{\sin^2(t^2)}\right| \quad \ln a - \ln b = \ln\frac{a}{b}, \quad C \ln a = \ln a^c$$

$$u' = \frac{t}{\sin^2(t^2)}$$

Integrate again:  $u = \int \frac{t}{\sin^2(t^2)} dt \quad \frac{1}{\sin^2 t} = \csc^2 t$ .

$$= \frac{-1}{2} \int \csc(t^2) \cdot d(t^2)$$

$$= \frac{-1}{2} \cot(t^2)$$

$$\int \csc^2 t = -\cot t + C.$$

again we don't care about  $C$ .

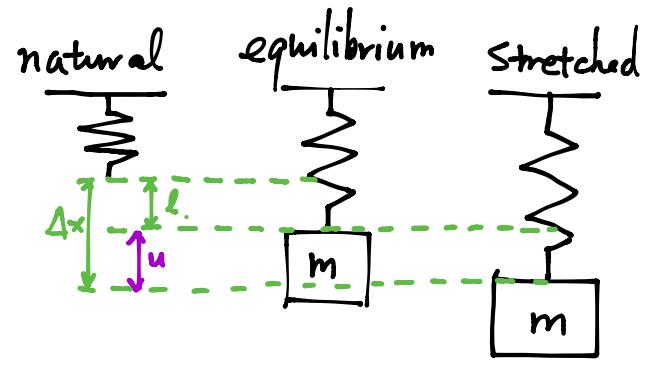
$$y_2 = u y_1 = -\frac{1}{2} \cot(t^2) \cdot \sin(t^2) = -\frac{1}{2} \cos(t^2)$$

General solution:  $y = C_1 \sin(t^2) + C_2 (-\frac{1}{2} \cos(t^2))$

$$= C_1 \sin(t^2) + C_2 \cos(t^2).$$

Free Vibrations.

A mass is attached with a spring vertically. The mass is subject to:



① gravity =  $mg$

② force of the spring =  $k \Delta x$        $\Delta x$  = displacement of the spring from the natural length.  
(Hooke's law)

③ Damping force =  $\gamma u'$  with direction opposite to the direction of motion and being proportional to the velocity.

Let  $u$  be the displacement of the mass from the equilibrium. Take downside to be the positive direction.

$$m \frac{d^2u}{dt^2} = mg - k \Delta x - \gamma u'$$

Since  $mg = kl$ ,  $mg - k \Delta x = kl - k \Delta x = -k(\Delta x - l) = -ku$ .

$$\Rightarrow mu'' = -ku - \gamma u' \Rightarrow mu'' + \gamma u' + ku = 0.$$

Case 1: Undamped case:  $\gamma = 0$ .

The ODE becomes:  $mu'' + ku = 0$

$$\text{Char. eqn: } mr^2 + k = 0 \Rightarrow r^2 = -\frac{k}{m} \Rightarrow r = \pm i\sqrt{\frac{k}{m}} \cdot i$$

$$\text{Gen. soln: } u = C_1 \cos\left(\sqrt{\frac{k}{m}}t\right) + C_2 \sin\left(\sqrt{\frac{k}{m}}t\right)$$

$$\text{Write } \omega = \sqrt{\frac{k}{m}}. \text{ Gen. soln} = C_1 \cos \omega t + C_2 \sin \omega t.$$

With initial value specified, we can solve  $C_1, C_2$  as concrete numbers.

$$\begin{aligned} u &= C_1 \cos \omega t + C_2 \sin \omega t \\ &= \sqrt{C_1^2 + C_2^2} \cos(\omega t - \varphi) \end{aligned}$$

$$\text{Natural frequency: } \omega = \sqrt{\frac{k}{m}} \quad \text{Period: } \frac{2\pi}{\omega}$$

$$\text{Amplitude: } A = \sqrt{C_1^2 + C_2^2}$$

Phase:  $\varphi$ , determined by the angle of  $(C_1, C_2)$  on the plane.

$$\text{Example: } mg = 10 \text{ lb}, \quad 10 \text{ lb} = k \cdot 2 \text{ in.} = k \cdot \frac{1}{6} \text{ ft.}$$

$$u(0) = 2 \text{ in} = \frac{1}{6} \text{ ft} \quad u'(0) = -1 \text{ ft/s.}$$

$$\text{ODE: } mu'' + ku = 0 \quad m = \frac{10 \text{ lb}}{32 \text{ ft/s}^2} = \frac{5}{8} \text{ lb} \cdot \text{s}^2/\text{ft}, \quad k = 60 \text{ lb}/\text{ft}.$$

$$\frac{5}{8}u'' + 60u = 0 \Rightarrow u'' + 96u = 0, \quad u(0) = \frac{1}{6}, \quad u'(0) = -1.$$

$$\text{Char. roots: } r = \pm \sqrt{96}i = \pm 4\sqrt{6}i$$

$$\text{Gen. soln: } u = C_1 \cos(4\sqrt{6}t) + C_2 \sin(4\sqrt{6}t)$$

$$u(0) = \frac{1}{6} \Rightarrow C_1 = \frac{1}{6}, \quad u'(0) = -1 \Rightarrow 4\sqrt{6}C_2 = -1 \Rightarrow C_2 = -\frac{1}{4\sqrt{6}}.$$

$$\text{Sol'n: } u = \frac{1}{6} \cos(4\sqrt{6}t) - \frac{1}{4\sqrt{6}} \sin(4\sqrt{6}t)$$

$$\text{Amplitude: } \sqrt{\frac{1}{36} + \frac{1}{96}} = \sqrt{\frac{1}{6 \times 6} + \frac{1}{16 \times 6}} = \sqrt{\frac{1}{12} \left(\frac{1}{3} + \frac{1}{8}\right)} = \sqrt{\frac{1}{12} \cdot \left(\frac{11}{12 \times 2}\right)}$$

$$= \frac{1}{12} \sqrt{\frac{11}{2}}$$

Stays constant  $\Rightarrow$  steady oscillation.

$$\text{Nat. Freq.} = 4\sqrt{6}. \quad \text{Period} = \frac{2\pi}{4\sqrt{6}} = \frac{\pi}{2\sqrt{6}}$$

$$\text{Phase: } \varphi = \arctan \frac{6}{4\sqrt{6}} = \arctan \frac{3}{2\sqrt{6}} = \arctan \frac{\sqrt{6}}{4}$$

H/W. Skip 3, 4, 5. 1a.

Attendance Quiz: Knowing  $y_1 = \frac{1}{t}$  is the sol'n of  $t^2y'' + 3ty' + y = 0$

Find the general sol'n.

LECTURE NOTES OF DIFFERENTIAL EQUATION

Lecture

Page

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Lecture

Page

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